Simulation of industrial ceramic powder forming process through non-standard material models and multi-objective optimization

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The Extremely Flexible BP Yield Function

The BP yield function is defined in terms of the stress tensor σ

$$F(\pmb{\sigma}) = f(p) + \frac{q}{g(\theta)},$$

where, defining the parameter Φ as

$$\Phi = \frac{p+c}{p_c+c},$$

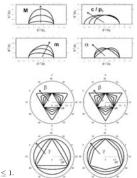
the meridian and deviatoric functions are respectively written as

$$f(p) = \begin{cases} -Mp_c\sqrt{(\Phi - \Phi^m)} \left[2(1 - \alpha)\Phi + \alpha\right], & \Phi \in [0, 1], \\ +\infty, & \Phi \notin [0, 1], \end{cases}$$

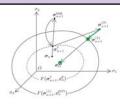
$$\frac{1}{a(\theta)} = \cos \left[\beta \frac{\pi}{6} - \frac{\cos^{-1}(\gamma \cos 3\theta)}{3}\right],$$

The yield function is convex when the seven material parameters defining the meridian shape function f(p) and the deviatoric shape function $g(\theta)$ lie within the following intervals

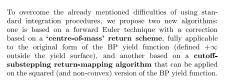




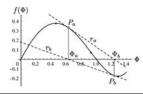
New Integration Algorithms

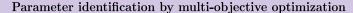


Used in the context of elastoplastic modelling, the BP yield function introduces the problem that for it to be convex, it has been defined $+\infty$ outside certain regions in the stress-space. Therefore, in its original form, the BP yield function cannot be implemented within an elastoplastic integration scheme, if a gradient-based return-mapping algorithm is used, for which the gradient of the yield function is needed everywhere in the



Another option is an implicit definition of the BP yield function, to avoid singularieties or wrong elastic domains certain regions in the stress-space. With this alternative formulation, the integration of the constitutive equations can be successfully performed with a standard fully implicit return-mapping procedure.





Some of the material parameters, involved in the constitutive model for ceramic powder densification, were

identifed directly from the results of a set of experimental tests All the other material parameters, not identified directly through the mechanical tests, are determined by

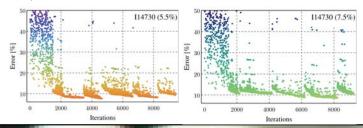
simulating the experiments and performing an iterative multi-objective optimization

The optimization has been carried out with simplified numerical models, involving a small number of finite

elements and neglecting the effects of friction.
This approach significantly **speed up** the FE simulations, so that the entire parameter identification could be

performed on a simple laptop computer in a reasonable computational time

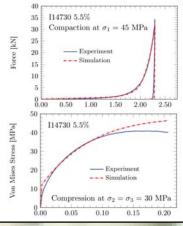
As a sufficiently precise starting point was not available, both global and local optimization methods have been used to efficiently estimate the material parameters. The "hybrid" procedure involves first a Pareto optimization, by means of moga (multi-objective genetic algorithm). After a sufficiently high number of iterations of the global algorithm, the best five solutions are refined by a local optimization method (pattern-

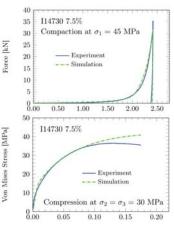


Comparison with experimental tests

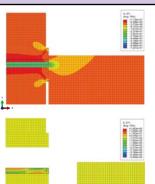
The following figures show the comparison between numerical and experimental results, for both uniaxial deformation tests and triaxial tests.

With the identified parameters, it is possible to obtain a good agreement between numerical and experimental results also in tests which are not considered in the optimization. This is an indication of the consistency of the constitutive model and of the validity of the optimization procedure. The two figures on the top show the uniaxial compaction (force vs. displacement) curves for water content w=5.5% (left) and w=7.5%(right). The bottom figures show the compression/extension triaxial (von Mises stress vs. axial strain) curves for water content w = 5.5% (left) and w = 7.5% (right).





Simulation of industrial powder compaction processes

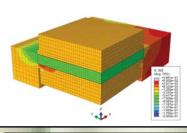


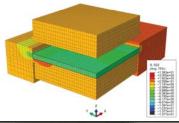
Finite element analyses, involving contact interaction and friction, have been performed to accurately reproduce the industrial processes of ceramic tablets and tiles forming. In these simulations, the complete forming device, composed by matrix, upper and lower punches, was modelled, and the interaction between each single part and the ceramic powder was taken into account.

The simulation comprises the following steps: geostatic step, in which an initial confinement p_0 is imposed on the powder; uniaxial compaction phase, in which the upper punch is loaded by the given vertical pressure; unloading step, in which the load on the upper punch is removed; extraction, in which the matrix is removed in order to simulate the removal of the tablet from the cylindrical

The stresses developing in the ceramic powder as well as in the mould are shown in the figures. The analysis made it also possible to investigate the influence of friction in the forming process and to determine the transversal pressure on the steel matrix. The capabilities of the model to predict **residual stresses**

are crucial, since residual stresses may lead to fracture of the green body, by end capping or lamination.





Density distribution in mesh-backed tiles after pressing

The **density distribution** in green bodies is of primary importance in the optimization of tile forming processes. In fact, non-uniform density can affect

the subsequent sintering process, resulting in **poor quality** of the final ceramic product. We notice higher void ratio values, corresponding to **lower density**, in correspondence of the protrusions. These results pave the way to more advanced virtual prototyping analyses, aiming at the opti-mization of the design of tile forming devices, in or-der to produce green bodies with improved density distribution.



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